

Poisson–Lie T–plurality as Canonical Transformation

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Outline

- 1 Elements of Poisson–Lie T–plurality
- 2 T–plurality transformation of extremal left–invariant fields
- 3 Transformation of canonical variables
- 4 Poisson–Lie T–plurality as canonical transformation

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Elements of Poisson–Lie T–duality of σ –models

The σ –models (without spectators) are given by the **action**

$$S[g] = \frac{1}{2} \int d^2x L_+(g) \cdot E(g) \cdot L_-^t(g) = \frac{1}{2} \int d^2x \partial_+ \phi^\mu \mathcal{E}_{\mu\nu}(\phi) \partial_- \phi^\nu \quad (1)$$

where the map g maps $V \subset \mathbb{R}^2$ into the group G whose Lie algebra has basis $\{T_a\}$,

$$L_\pm(g)^a := (g^{-1} \partial_\pm g)^a, \quad g^{-1} \partial_\pm g = L_\pm(g) \cdot T$$

$\phi^\mu : V \subset \mathbb{R}^2 \rightarrow \mathbb{R}^{\dim G}$ is the same map as g but written in some group coordinates,

$$L_\pm(g) = \partial_\pm \phi \cdot e^L \cdot T$$

and x_+, x_- are the light–cone coordinates on Minkowski \mathbb{R}^2

$$\tau = x_+ + x_-, \quad \sigma = x_+ - x_-.$$

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The basic idea of Poisson–Lie T–duality

C. Klimčík and P. Ševera, *Phys. Lett. B* 351 (1995) 455.

Under certain conditions the equations of motion of the σ –model can be written as equations on

Drinfel'd double

$(G|\tilde{G})$ – Lie group D whose Lie algebra \mathfrak{d} admits a decomposition $\mathfrak{d} = \mathfrak{g} \dot{+} \tilde{\mathfrak{g}}$ into a pair of subalgebras maximally isotropic with respect to a symmetric ad-invariant nondegenerate bilinear form $\langle \cdot, \cdot \rangle$.

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The matrices $E(g)$ for the dualizable σ –models are of the form

$$E(g) = [E_0^{-1} + \Pi(g)]^{-1}$$

where E_0 is a constant matrix,

$$\Pi(g) = b^t(g) \cdot a(g) = -\Pi(g)^t,$$

and $a(g), b(g)$ are submatrices of the adjoint representation of the subgroup G on the Lie algebra of the Drinfel'd double D .

The dual model

is obtained by the interchange

$$G \leftrightarrow \tilde{G}, \quad \mathfrak{g} \leftrightarrow \tilde{\mathfrak{g}}, \quad \Pi(g) \leftrightarrow \tilde{\Pi}(\tilde{g}), \quad E_0 \leftrightarrow E_0^{-1}.$$

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The equations of motion of the dualizable σ –model can be formulated as the equations on the Drinfel'd double

$$\langle l^{-1} \partial_{\pm} l, \mathcal{E}^{\mp} \rangle = 0,$$

where $l = \tilde{h}g \in D$, $\tilde{h} \in \tilde{G}$, $g \in G$ and

$$\mathcal{E}^+ = \text{span} \left(T + E_0 \cdot \tilde{T} \right), \quad \mathcal{E}^- = \text{span} \left(T - E_0^t \cdot \tilde{T} \right)$$

are two orthogonal subspaces in \mathfrak{d} . (The unique decomposition $l = \tilde{h}g$ on D exists for a general Drinfel'd double only in the vicinity of the group unit. For the so–called perfect Drinfel'd double \mathfrak{g} it is defined globally and we shall consider only these.)

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Poisson–Lie T–plurality

R. von Unge, J. High En. Phys. 02:07 (2002) 014.

Main idea:

In general there are **several decompositions** (Manin triples) of a Drinfel'd double.

Let $\hat{\mathfrak{g}} + \bar{\mathfrak{g}}$ be another decomposition of the Lie algebra \mathfrak{d} into maximal isotropic subalgebras. The dual bases of \mathfrak{g} , $\tilde{\mathfrak{g}}$ and $\hat{\mathfrak{g}}$, $\bar{\mathfrak{g}}$ are related by the linear transformation

$$\begin{pmatrix} T \\ \tilde{T} \end{pmatrix} = \begin{pmatrix} K & Q \\ R & S \end{pmatrix} \begin{pmatrix} \hat{T} \\ \bar{T} \end{pmatrix}, \quad (2)$$

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The duality of both bases (i.e. $\langle T_a, \tilde{T}^b \rangle = \delta_a^b$) requires

$$\begin{pmatrix} K & Q \\ R & S \end{pmatrix}^{-1} = \begin{pmatrix} S^t & Q^t \\ R^t & K^t \end{pmatrix}.$$

Besides that, the matrices K, Q, R, S are chosen in such a way that the structure constants of the Lie algebra \mathfrak{d}

$$\begin{aligned} [T_a, T_b] &= f_{ab}{}^c T_c, \\ [\tilde{T}^a, \tilde{T}^b] &= \tilde{f}^{ab}{}_c \tilde{T}^c, \\ [\tilde{T}^a, T_b] &= f_{bc}{}^a \tilde{T}^c - \tilde{f}^{ac}{}_b T_c \end{aligned}$$

transform to similar ones where the structure constants f, \tilde{f} of \mathfrak{g} and $\tilde{\mathfrak{g}}$ are replaced by the structure constants \hat{f}, \bar{f} of $\hat{\mathfrak{g}}$ and $\bar{\mathfrak{g}}$ and $T \rightarrow \hat{T}, \tilde{T} \rightarrow \bar{T}$.

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The σ –model related by the Poisson–Lie T–plurality

to (1) is defined analogously to (1) but with

$$\begin{aligned}\widehat{E}(\widehat{g}) &= (\widehat{E}_0^{-1} + \widehat{\Pi}(\widehat{g}))^{-1}, \\ \widehat{\Pi}(\widehat{g}) &= \widehat{b}^t(\widehat{g}) \cdot \widehat{a}(\widehat{g}) = -\widehat{\Pi}(\widehat{g})^t, \\ \widehat{E}_0 &= (K + E_0 \cdot R)^{-1} \cdot (Q + E_0 \cdot S)\end{aligned}$$

Relation between the classical solutions of the two σ –models is obtained from two possible decompositions of $l \in D$

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T–plurality transformation of extremal left–invariant fields

We derive the formulae for transformation of left–invariant fields evaluated on solutions of equations of motion (hence extremal).

This will enable us to get

- Transformation of boundary conditions for the classical solutions of the σ –models (a generalization of [Cecilia Albertsson, Ronald A. Reid-Edwards, \[hep-th/0606024\]](#)).
- Transformation of canonical variables of the σ –models.

We write the **left–invariant field** $l^{-1}\partial_+l$ on the Drinfel'd double

$$\begin{aligned} l^{-1}\partial_+l &= (\tilde{h}g)^{-1}(\partial_+(\tilde{h}g)) = L_+(g) \cdot T + \tilde{L}_+(\tilde{h}) \cdot g^{-1}\tilde{T}g \\ &= L_+(g) \cdot T + \tilde{L}_+(\tilde{h}) \cdot [b(g) \cdot T + a^{-t}(g) \cdot \tilde{T}] \end{aligned}$$

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and the definition of $E(g)$ we get

$$l^{-1} \partial_+ l = L_+(g) \cdot E(g) \cdot \left[E_0^{-1} \cdot T + \tilde{T} \right]. \quad (3)$$

Similarly, from the decomposition $l = \bar{h} \hat{g}$

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the formula for transformation of the left–invariant fields under the Poisson–Lie T–plurality

$$\widehat{L}_+(\widehat{g}) = L_+(g) \cdot E(g) \cdot [S + E_0^{-1} \cdot Q] \cdot \widehat{E}^{-1}(\widehat{g}) \quad (5)$$

In the same way we can derive

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Transformation of canonical variables

The **canonical momentum** is found from the action (1)

$$\mathcal{P}_\mu = \frac{\partial \mathcal{L}}{\partial (\partial_\tau \phi^\mu)} = \frac{1}{2} (\mathcal{E}_{\mu\nu} \partial_- \phi^\nu + \mathcal{E}_{\nu\mu} \partial_+ \phi^\nu). \quad (6)$$

We shall use the momentum in local frame $\mathcal{P}_a = v^L{}_a{}^\mu(g) \mathcal{P}_\mu$, where $v^L = (e^L)^{-1}$ and write it as the column vector \mathcal{P}

$$\mathcal{P} = \frac{1}{2} (E(g) \cdot L_-^t(g) + E^t(g) \cdot L_+^t(g)).$$

We also define

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Using the similar expressions for the canonical variables after T–plurality transformation and the formulae for transformation of $L_{\pm}(g)$ (5) we find the generalization of the transformation found in T–duality case in [K. Sfetsos, Nucl. Phys. B \(Proc. Suppl.\) 56 \(1997\) 302](#) and [K. Sfetsos, Nucl.Phys. B 517 \(1998\) 549-566](#) to the T–plurality case, i.e.

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$$\begin{aligned}\hat{\mathcal{P}} &= (Q^t \cdot \Pi(g) + S^t) \cdot \mathcal{P} + Q^t \cdot L_{\sigma}^t, & (7) \\ \hat{L}_{\sigma} &= \mathcal{P}^t \cdot \left[(S - \Pi(g) \cdot Q) \cdot \hat{\Pi}(\hat{g}) + R - \Pi(g) \cdot K \right] \\ &\quad + L_{\sigma} \cdot \left(Q \cdot \hat{\Pi}(\hat{g}) + K \right).\end{aligned}$$

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Poisson–Lie T–plurality as canonical transformation

In order to show that (7) is really a canonical transformation we shall use the expressions for Poisson brackets of \mathcal{P}_a and

$$\mathcal{J}^a = L_\sigma^a + \Pi(g)^{ab}\mathcal{P}_b, \quad \mathcal{J} = L_\sigma^t + \Pi(g) \cdot \mathcal{P} \quad (8)$$

$$\{\mathcal{J}^a, \mathcal{J}^b\} = \tilde{f}^{ab}{}_c \mathcal{J}^c \delta(\sigma - \sigma'),$$

$$\{\mathcal{P}_a, \mathcal{P}_b\} = f_{ab}{}^c \mathcal{P}_c \delta(\sigma - \sigma'),$$

$$\{\mathcal{J}^a, \mathcal{P}_b\} = (f_{bc}{}^a \mathcal{J}^c - \tilde{f}^{ac}{}_b \mathcal{P}_c) \delta(\sigma - \sigma') + \delta_b^a \delta'(\sigma - \sigma').$$

These Poisson brackets are equivalent to the canonical ones

$$\begin{aligned} \{\mathcal{P}_\mu, \mathcal{P}_\nu\} &= \{\partial_\sigma \phi^\mu, \partial_\sigma \phi^\nu\} = 0, \\ \{\partial_\sigma \phi^\mu, \mathcal{P}_\nu\} &= \delta_\nu^\mu \delta'(\sigma - \sigma'). \end{aligned} \quad (9)$$

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We find that the Poisson brackets can be written in the compact form

$$\{\mathcal{Y}_\alpha, \mathcal{Y}_\beta\} = \mathcal{F}_{\alpha\beta}{}^\gamma \mathcal{Y}_\gamma \delta(\sigma - \sigma') + \mathcal{B}_{\alpha\beta} \delta'(\sigma - \sigma') \quad (10)$$

where $\alpha, \beta, \gamma = 1, \dots, \dim \mathfrak{d}$,

$$\mathcal{Y} = \begin{pmatrix} \mathcal{P} \\ \mathcal{J} \end{pmatrix},$$

$\mathcal{F}_{\alpha\beta}{}^\gamma$ are structure constants of the Drinfel'd double and $\mathcal{B}_{\alpha\beta}$ are matrix elements of the bilinear form $\langle \cdot, \cdot \rangle$ in the basis T_a, \tilde{T}^a of \mathfrak{d} .

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$$\begin{aligned}\widehat{\mathcal{P}} &= S^t \cdot \mathcal{P} + Q^t \cdot \mathcal{J}, \\ \widehat{\mathcal{J}} &= R^t \cdot \mathcal{P} + K^t \cdot \mathcal{J}\end{aligned}\tag{11}$$

which reminds of the transformation of the basis elements of the Drinfel'd double

$$\begin{pmatrix} \widehat{T} \\ \widehat{\bar{T}} \end{pmatrix} = \begin{pmatrix} S^t & Q^t \\ R^t & K^t \end{pmatrix} \begin{pmatrix} T \\ \bar{T} \end{pmatrix}.$$

Consequently, Poisson brackets (10) are form–invariant under the transformation (11). Therefore, **the canonical Poisson brackets are invariant**, i.e. (9) is transformed by Poisson–Lie T–plurality to

$$\begin{aligned}\{\widehat{\mathcal{P}}_\mu, \widehat{\mathcal{P}}_\nu\} &= \{\partial_\sigma \widehat{\phi}^\mu, \partial_\sigma \widehat{\phi}^\nu\} = 0, \\ \{\partial_\sigma \widehat{\phi}^\mu, \widehat{\mathcal{P}}_\nu\} &= \delta_\nu^\mu \delta'(\sigma - \sigma').\end{aligned}$$

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The preservation of the Hamiltonian density

Finally, we compute the **Hamiltonian density**

$$\begin{aligned}
 \mathcal{H} &= \partial_\tau \phi^\mu \mathcal{P}_\mu - \mathcal{L} \\
 &= \frac{1}{4} \left(L_-(g) \cdot E(g) \cdot L_-^t(g) + L_+(g) \cdot E(g) \cdot L_+^t(g) \right)
 \end{aligned}$$

where $L_\pm(g)$ are expressed in terms of \mathcal{P}, L_σ . Similarly,

$$\widehat{\mathcal{H}} = \frac{1}{4} \left(\widehat{L}_-(\widehat{g}) \cdot \widehat{E}(\widehat{g}) \cdot \widehat{L}_-^t(\widehat{g}) + \widehat{L}_+(\widehat{g}) \cdot \widehat{E}(\widehat{g}) \cdot \widehat{L}_+^t(\widehat{g}) \right).$$

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Thank you for you attention